SURVEY ON CROP IRIS IMAGE FROM FACIAL IMAGE

R.ArunaRani¹ D.M.D.Preethi²

 ¹PG Scholar, Department of Computer Science and Engineering, PSNA college of Engineering and Technology, Dindigul -624619, India.
²Assistant Professor, Department of Computer Science and Engineering, PSNA college of Engineering and Technology, Dindigul -624619, India.

ABSTRACT: Iris authentication is one of the developing research fields in the biometrics. An efficient algorithm is designed to automatically segment the iris from the facial image. Iris segmentation is an essential module in iris recognition because it defines the effective image region used for subsequent processing such as feature extraction. Traditional iris segmentation methods often involve an exhaustive search of a large parameter space, which is time consuming and sensitive to noise. The features are perfectly extracted from eye image using the feature extraction techniques in order to remove the noisy data's from the extracted image. Then the extracted features are given to the classifier. Later on this work will be helps to identify an individual by comparing the feature obtained from the feature extraction algorithm with the previously stored feature by producing a similarity score. This score will be indicating the degree of similarity between a pair of biometrics data under consideration. Depending on degree of similarity, individual can be identified.

KEYWORDS: Biometric system, Segmentation, Feature extraction using GLCM approach.

1. INTRODUCTION

Reliable identification of people is required for many applications such as immigration control, aviation security, or safeguarding of financial transactions. Commonly used biometric features include face, fingerprints, voice, facial thermo grams, iris, retina, gait, palm-prints, hand geometry,

Research and experience to date in actual etc. applications have demonstrated that the texture of a person's iris is unique and can be used as a means of identification. Improving the accuracy and reliability of iris recognition is the goal of many current research endeavors. The annular region of the iris is unwrapped or transformed from raw image coordinates to normalized polar coordinates. Compared with other biometric features, the iris is more stable and reliable for identification. Furthermore, since the iris is an externally visible organ, iris-based personal identification systems can be noninvasive to their users which are of great importance for practical applications. The original approach to the segmentation task was proposed by Daugman and consisted in the maximization of an integro differential operator. In a different approach, Wildes suggested a method involving edge detection followed by circular Hough transform. Daugman uses an integrodifferential operator for segmenting the iris. It finds both inner and the outer boundaries of the iris region. The outer as well as the inner boundaries are referred to as limbic and pupil boundaries. The parameters such as the center and radius of the circular boundaries are being searched in the three dimensional parametric space in order to maximize the evaluation functions involved in the model. Then the segmented iris image is classified using classifiers. The classifiers are used to classify the extracted features. Then the matching is performed with that of the original image to prove the authentication.

2. OVERVIEW OF IRIS RECOGNITION

2.1 Personal Identification Based On Iris Texture Analysis

This paper [6] presents a new method for identifying individuals from an iris image sequence. We thus perform a series of experiments to evaluate its performance. Moreover, the comparison with the proposed method with some existing methods for iris recognition and present detailed discussions on the overall experimental results. The bootstrap, which provides a powerful approach to estimating the underlying distribution of the observed data using computer-intensive methods, is adopted to estimate the error rates of a biometric method. The description about an efficient- method for personal identification from an iris image sequence and a quality descriptor based on the Fourier spectra of two local regions in an iris image is defined to discriminate clear iris images from low quality images due to motion blur, defocus, and eyelash occlusion. According to the distinct distribution of the iris characteristics, a bank of spatial filters is constructed for efficient feature extraction. It has been proven that the defined spatial filter is suitable for iris recognition. The experimental results have demonstrated the effectiveness of the proposed method. A detailed performance comparison of existing methods for iris recognition has been conducted on the CASIA Iris Database. Such comparison and analysis is used to further improve the performance of the iris recognition methods.

2.2 FPGA Implementation of Face Detection

This paper [12] proposes a system for face detection using Adaboost algorithm. The system also uses the skin color information. However, color is not a physical phenomenon. Thus face detection is known to be highly influenced by these conditions. The proposed face detection engine renders high performance face detection rate by producing reliable and optimized learning data through the Adaboost learning algorithm. In order to reduce false detection by a non face or other face like objects, skin color and depth data should be considered. On face detection process, images are classified based on values of sample features rather than pixels. These feature values are calculated using haar features, originally given by Viola & Jones. Adaboost constructs a collection of weak classification functions which is called as a Strong Classifier. Each feature is considered to be a potential weak classifier which correctly classifies in little more than half of the cases. The best feature is selected by evaluating the feature on a set of training images. Weighed error is a function of weights of each training images. The weight of correctly classified image is decreased while the weight of misclassified images unchanged the proposed approach is found to be reasonably accurate given its simplicity. The hardware architecture for real-time processing will be implanted on a FPGA. With satisfactory results on hand, the proposed approach can be adopted to simplify the process of face recognition, face expression detection or any other object detection.

2.3 Iris Images Captured On-the-Move and At-a-Distance

The main purpose of this paper [9] is to announce the availability of the UBIRIS.v2 database, a multisession iris images database which singularly contains data captured in the visible wavelength, at-adistance (between four and eight meters) and on onthe-move. This database is freely available for researchers concerned about visible wavelength iris recognition and will be useful in accessing the feasibility and specifying the constraints of this type of biometric recognition. UBIRIS database is released in 2004. Our purpose was to simulate less constrained imaging processes and acquire visible wavelength images with several types of data occluding the iris rings. A large number of experiments were conducted on this database and reported in the literature, although the realism of its noise factors received some criticisms. This was a major motivation for the development of a new version of the database (UBIRIS.v2) in which the images were actually captured in non constrained conditions (at-a-distance, on-the-move, and on the visible wavelength), with correspondingly more realistic noise factors. The major purpose of the UBIRIS.v2 database is to constitute a new tool to evaluate the feasibility of visible wavelength iris recognition under far from ideal imaging conditions. When planning the UBIRIS.v2 database, we had three basic concerns: to acquire images, first, of moving subjects, second, at varying imaging distances, and finally, to incorporate noise factors that realistically result from nonconstrained and

varying lighting environments. In this paper, the availability of the UBIRIS.v2 iris image database and the used imaging framework and acquisition protocol is described. Also, the results about the amount of information that it is possible to capture through the used acquisition setup, reported measures of separatability between the resultant iris signatures, and confirmed the major impact that the levels of iris pigmentation have in the recognition feasibility. The UBIRIS.v2 database is a valuable tool for the specification of the limits for the visible wavelength and non constrained iris recognition, namely, the required lighting conditions, imaging distance, subject movements, and perspectives. Finally, conclusion is that type of recognition is also conditioned by the development of alternate iris segmentation and noise detection strategies, able to deal with a higher range of data heterogeneity.

2.4 Accurate and Fast Iris Segmentation for Iris Biometrics

Speed is often a bottleneck in practical applications, and iris segmentation is often found to be the most time-consuming module in an iris recognition system. Being the first step in iris recognition, iris segmentation defines the image contents used for feature extraction and matching, which is directly related to the recognition accuracy and it is reported that most failures to match in iris recognition result from inaccurate iris segmentation. However, several challenges are noted in practical iris segmentation. For example, the irises often partially occluded by eyelids, eyelashes, and shadows (EES), especially for oriental users. It can also be occluded by speculars reflections when the user wears glasses. Moreover, it is found that often, the pupillary and limbic boundaries are noncircular and therefore can lead to inaccuracy if fitted with simple shape assumptions. Other challenges of iris segmentation include defocusing, motion blur, poor contrast, oversaturation, etc. All of these challenges make iris segmentation difficult, therefore an accurate, fast, and robust iris segmentation algorithm is highly desirable and deserves more effort. Daugman used the integrodifferential operator serves as a circle finder which searches the maximum angular integral of radial derivative over the image domain. Iris boundaries were localized via edge detection followed by Hough transforms. Both algorithms achieve encouraging performance. In response to these challenges in iris segmentation and drawbacks of the traditional algorithms, many new and improved iris segmentation algorithms have been proposed. In this paper [13], an accurate and fast iris segmentation algorithm for iris biometrics. With the learned Adaboost- cascade iris detector, non-iris images are excluded before further processing so that unnecessary computation is avoided. Extensive experimental results on three challenging iris image databases show that the proposed method achieves state-of-the-art iris segmentation accuracy, while being computationally much more efficient.

2.5 Fusion of Hamming Distance and Fragile Bit Distance

The most common iris biometric algorithm in [4] represents the texture of an iris using a binary iris code. Not all bits in an iris code are equally consistent across different images of the same iris. A bit is deemed fragile if its value changes across iris codes created from different images of the same iris. Previous research has shown that iris recognition performance can be improved by masking these fragile bits. Rather than ignoring fragile bits completely. The concept is that some bits in the iris code are less consistent than others. For creating an iris code, a traditional iris biometrics system applies Gabor filters to a number of locations on an iris image and obtains a complex- valued filter response for each location. Each complex number is quantized to two bits; the first bit is set to one if the real part of the complex number is positive, and the second bit is one if the imaginary part is positive. Consider multiple images of the same iris. For a filter applied to a specific location in a single image, if the real part of the complex number has a large magnitude, then the corresponding bit will likely be consistent and if the real part is close to zero, the corresponding bit is fragile. Similar logic applies to the imaginary bits. The iris structure is generally considered highly robust, changing very little over time. This concept suggests a simple optimization to iris recognition algorithms. However, the physical locations of those bits should be stable and might be used to improve our iris recognition performance. In this paper, a new

metric is defined, the fragile bit distance, which measures how two fragile bit masks differ. Fusion of FBD and Hamming distance is a better classifier than using Hamming distance alone. Fusion can be done either by using a weighted average of FBD and Hamming distance or by multiplying. The multiplication of FBD and Hamming distance reduces the EER of our iris recognition system. Fusing FBD and Hamming distance has a greater benefit when higher levels of fragile bit masking are used. At low levels of fragile bit masking, fusion had similar results to using Hamming distance alone on the data. When using fragile bit masking thresholds of 15 percent or greater, fusion had superior performance.

2.6 Iris Occlusion Estimation Method Based on High-Dimensional Density Estimation

Iris masks play an important role in iris recognition. They indicate which part of the iris texture map is useful and which part is occluded or contaminated by noisy image artifacts such as eyelashes, eyelids, eyeglasses frames, and specular reflections. The accuracy of the iris mask is extremely important. The performance of the iris recognition system will decrease dramatically when the iris mask is inaccurate, even when the best recognition algorithm is used. Traditionally, people use rule-based algorithms to estimate iris masks from iris images. Experimental results show that the masks generated by the proposed algorithm increase the iris recognition rate on both ICE2 and UBIRIS dataset, verifying the effectiveness and importance of the proposed method for iris occlusion estimation. There are two main advantages of this coordinate transformation. First, it normalizes the texture variation caused by changes in environmental illumination which lead to pupil dilation and contraction. The second advantage of this coordinate transformation is that it translates the rotational shift, i.e., eyeball inplane rotation due to head tilt, in the Cartesian coordinate system into a pure translational shift in horizontal direction in the polar domain. The goal of this mask is to indicate which part in the iris map is truly iris texture and which part is noise. The accuracy of the iris masks has a great impact on the recognition accuracy of the iris recognition systems. Traditionally, the main focus of iris recognition

research addresses the power of the matching algorithm and the feature extraction. Accurate iris masks, combined with good features and effective recognition schemes, make the iris recognition systems more successful. However, if the iris masks are inaccurate, the best feature extraction and recognition algorithms cannot compensate for such flaws. The overall recognition rate will decrease dramatically because the region of the invalid iris is used during feature extraction and matching. Robustly estimating iris masks is one of the key factors to achieve high iris recognition rates. In this work, we have five contributions. The experimental results [15] show that the proposed method can detect the occluded regions in an iris in polar form, and the detection result (the iris mask) is very similar to a manually created mask and is very efficient in the test stage, which is another important advantage when being used in a practical online recognition system. One possible direction for future work is that is to combine the proposed method with another existing method to see further improve the iris recognition accuracy. Also, we can try to use the proposed framework directly on iris images in Cartesian form to see if it also works

2.7 Feature Extraction Using GLCM

Feature extraction involves simplifying the amount of resources required to describe a large set of data accurately. When performing analysis of complex data one of the major problems stems from the number of variables involved. Analysis with a large number of variables generally requires a large amount of memory and computation power or a classification algorithm which over fits the training sample and generalizes poorly to new samples. Feature extraction is a general term for methods of constructing combinations of the variables to get around these problems while still describing the data with sufficient accuracy. Texture analysis aims in finding a unique way of representing the underlying characteristics of textures and represent them in some simpler but unique form, so that they can be used for robust, accurate classification and segmentation of objects. In this paper [19], Gray level co- occurrence matrix is formulated to obtain statistical texture features. A number of texture features may be extracted from the GLCM. Only four second order

features namely angular second moment, correlation, inverse difference moment, and entropy are computed. These four measures provide high discrimination accuracy required for motion picture estimationIn statistical texture analysis, texture features are computed from the statistical distribution of observed combinations of intensities at specified positions relative to each other in the image. The Gray Level Co occurrence Matrix (GLCM) method is a way of extracting second order statistical texture features. The approach has been used in a number of applications, Third and higher order textures consider the relationships among three or more pixels. These are theoretically possible but not commonly implemented due to calculation time and interpretation difficulty. Gray Level Co-Occurrence Matrix (GLCM) has proved to be a popular statistical method of extracting textural feature from images. In this paper four important features, Angular Second Moment (energy), (inertia moment), Correlation, Entropy, and the Inverse Difference Moment are selected for implementation. The Gray Level Coocurrence Matrix (GLCM) method is used for extracting four Statistical Texture Parameters i.e., Entropy, Inverse Difference Moment, Angular Second Moment and Correlation. These features are useful in motion estimation of videos and in real time pattern recognition applications like Military & Medical Applications.

2.8 Biometric Pattern Recognition

In this paper, a new biometric-based Iris feature extraction system [2] is proposed. The system automatically acquires the biometric data in numerical format (Iris Images) by using a set of properly located sensors. Iris Images are typically color images that are processed to gray scale images. Then the Feature extraction algorithm is used to detect "IRIS Effective Region (IER)" and then extract features from "IRIS Effective Region (IER)" that are numerical characterization of the underlying biometrics. Later on this work will be helping to identify an individual by comparing the feature obtained from the feature extraction algorithm with the previously stored feature by producing a similarity score. This score will be indicating the degree of similarity between a pair of biometrics data under consideration. Depending on degree of similarity, individual can be identified. From this n number of IRIS Patterns one single 'IRIS Pattern' of an individual can be generated by Statistical Analysis, which can be strongly used for Pattern Recognition or over all Human Recognition. In this work a huge IRIS Database is used for testing. By considering Biological characteristics of IRIS use of Statistical Correlation Coefficient for this 'IRIS Pattern' recognition where Statistical Estimation Theory can play a big role.

2.9 Phase-Based Image Matching

This paper [5] presents an efficient algorithm for iris recognition using phase-based image matching an image matching technique using phase components in 2D Discrete Fourier Transforms (DFTs) of given images. Experimental evaluation using the CASIA iris image databases (versions 1.0 and 2.0) and Iris Challenge Evaluation (ICE) 2005 database clearly demonstrates that the use of phase components of iris images makes it possible to achieve highly accurate iris recognition with a simple matching algorithm. In order to reduce the size of iris data and to prevent the visibility of iris images, the idea of 2D Fourier Phase Code (FPC) for representing iris information is introduced. The 2D FPC is particularly useful for implementing compact iris recognition devices using state-of-the-art Digital Signal Processing (DSP) technology. In this algorithm, 2D Gabor filters are used to extract a feature vector corresponding to a given iris image. The proposed matching algorithm assumes the use of iris images registered in the system to achieve high performance. Thus, the phase- based image matching provides a truly unified methodology for fingerprint, palm print, and iris recognition, which will be particularly useful for developing multimodal biometric applications in the future. Another important point to be noted is that the correlation filter based techniques for biometric authentication .They propose potential ideas for reducing the computational complexity in correlation-based pattern recognition. Detailed investigations in this direction are left for the future study.

2.10 Iris Authentication using SIFT with SVM

The proposed system [18] is Iris authentication using SIFT with SVM. This method provides best, accurate matching between two set of Iris. Iris authentication is one of the developing research fields in the biometrics. The features of the Iris image is extracted using SIFT algorithm. The features are perfectly extracted from eye image using this algorithm. Then the extracted features are given to the SVM classifier. The support vector machine is used as a classifier, it accurately matches the two set of iris features quickly. In the proposed method, there are two phases, used to authenticate the genuine user used. The features of Iris are extracted using the Scale Invariant Feature Transform (SIFT). The extracted features are classified using the support vector machine (SVM). The classified results are stored in the data base. The first two process of feature extraction and classification is same for both enrolment and verification process. The features are extracted and classified from query input image using SIFT and SVM. The matching process is to be performed using classified query image with the data stored image. If the matching process is successful, the person is an authenticated one; else the person is not a valid one. The key points are extracted from the iris image then it is given to the Support Vector Machine classifier. The classifier classifies the key points and produces the data and they are stored in the data base. In the verification phase the same process is repeated and the classification results are verified with the data base where the data are already stored based on the result the person can be identified as whether he is authenticated person or not. The experimental results shows that the obtained result is most fast and accurate compared to other techniques which are used already.

3. SUMMARY

In past years, several iris segmentation algorithms have been designed and most of this algorithm is developed for segmenting iris images in a constrained environment. To overcome past iris recognition system which operates at stop-and-stare mode, the images are acquired using visible illumination by high resolution cameras at a distance. Iris segmentation plays an important role and it is difficult process in the iris recognition system and the main goal of the segmentation process is to locate the iris boundaries namely inner

boundary and the outer boundary and hence to localize the eyelids. It is performed mainly by the integro-differential operator and hough transforms to segment the texture of iris images. Both algorithms provide accuracy but they are computationally complex and time consumption is large to have initial centre of the iris boundaries. Hence an automated algorithm for the remote identification of human at a distance which robustly segments the iris image from the acquired facial image and the performance analysis is performed. The pupil and iris boundaries are located based on a integro-differential constellation model, an approach to speed the performance of algorithm. Viola Jones based face and eye-pair detector is used to locate the face and iris region from the acquired facial image. For the classification of the image pixels neural network is constructed, which process information by their dynamic state response to external inputs. To overcome the misclassification of the image pixels due to different classifiers, a set post classification process is developed and it is highly effective in reducing the segmentation error.

4. CONCLUSION

Biometric technique uses physiological characteristics such as face, finger print, palm, iris voice etc. The iris is well suitable for the verification and authentication of human due to its distinctiveness and stable spatial patterns. From the face images, iris image can be captured then segmented and classified. Viola Jones based face/eye pair detector is used for face and eye detection. Histogram based segmentation approach is used for segmentation processes. The feature extraction process is used to extract the features from the segmented image. The extracted features are classified using the SVM classifier which is very fast supervised classification algorithm. The proposed approach is to measure the performance among the different classifiers and the authentication is verified with the original iris image and the classified iris. The robust approach is used for the person identification and authentication.

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