

SαRPS -Closed Maps and *SαRPS* -Open Maps in Topological Spaces

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Abstract- In this paper, the authors introduce *sαrps*-closed maps and *sαrps*-open maps in topological spaces and study some of their basic properties.

Keywords: *sαrps*-closed maps, *sαrps*-open maps.

I. INTRODUCTION

Different types of generalized closed maps and generalized open maps were studied by various researchers. Recently the authors introduced *sαrps*-closed sets and *sαrps*-open sets in topological spaces. Using these two sets, the authors introduce *sαrps*-closed maps and *sαrps*-open maps in topological spaces and continue the study of their relationship with various generalized closed maps and open maps.

II. PRELIMINARIES

Throughout this paper X and Y represent the topological spaces on which no separation axioms are assumed unless otherwise mentioned. For a subset A of a topological space X , clA and $intA$ denote the closure of A and the interior of A respectively. $X \setminus A$ denotes the complement of A in X . We recall the following definitions.

Definition 2.1:

A subset A of a space X is called

- (i) semi-open [9] if $A \subseteq cl\ int A$ and semi-closed if $int\ cl A \subseteq A$.
- (ii) α -open [17] if $A \subseteq int\ cl\ int A$ and α -closed if $cl\ int\ cl A \subseteq A$.
- (iii) regular open [21] if $A = int\ cl A$ and regular closed if $cl\ int A = A$.

Definition 2.2:

A subset A of a space X is called

- (i) generalized closed [10] (briefly g -closed) if $clA \subseteq U$ whenever $A \subseteq U$ and U is open.
- (ii) regular generalized closed [18] (briefly rg -closed) if $clA \subseteq U$ whenever $A \subseteq U$ and U is regular open.
- (iii) α -generalized closed [12] (briefly αg -closed) if $\alpha clA \subseteq U$ whenever $A \subseteq U$ and U is open.
- (iv) generalized semi-closed [3] (briefly gs -closed) if $sclA \subseteq U$ whenever $A \subseteq U$ and U is open.
- (v) generalized pre-regular closed [7] (briefly gpr -closed) if $pclA \subseteq U$ whenever $A \subseteq U$ and U is regular open.
- (vi) generalized semi-pre-closed [6] (briefly gsp -closed) if $spclA \subseteq U$ whenever $A \subseteq U$ and U is open.

- (vii) weakly generalized closed [16] (briefly wg -closed) if $cl\ int A \subseteq U$ whenever $A \subseteq U$ and U is open.
- (viii) regular weakly generalized closed [23] (briefly rwg -closed) if $cl\ int A \subseteq U$ whenever $A \subseteq U$ and U is regular open.
- (ix) generalized b -closed [1] (briefly gb -closed) if $bclA \subseteq U$ whenever $A \subseteq U$ and U is open.
- (x) regular generalized b -closed [14] (briefly rgb -closed) if $bclA \subseteq U$ whenever $A \subseteq U$ and U is regular open.

Definition 2.3 [22]

A subset A of a space X is called semi α -regular pre-semi closed (briefly *sαrps*-closed) if $sclA \subseteq U$ whenever $A \subseteq U$ and U is *αrps*-open.

The complements of the above mentioned closed sets are their respective open sets. For example, a subset B of a space X is generalized open (briefly g -open) if $X \setminus B$ is g -closed.

Definition 2.4

A map $f: (X, \tau) \rightarrow (Y, \sigma)$ is called semi-closed [9] (resp. regular closed [11], resp. α -closed [15], resp. gs -closed [24], resp. gsp -closed [6], resp. gb -closed [24], resp. rgb -closed [8], resp. g -closed [13], resp. αg -closed [5], resp. wg -closed [16], resp. rwg -closed [16], resp. rg -closed [2], resp. gpr -closed [7]) if for every closed subset F of (X, τ) , the set $f(F)$ is semi-closed (resp. regular closed, resp. α -closed, resp. gs -closed, resp. gsp -closed, resp. gb -closed, resp. rgb -closed, resp. g -closed, resp. αg -closed, resp. wg -closed, resp. rwg -closed, resp. rg -closed, resp. gpr -closed) in (Y, σ) .

Definition 2.5

A map $f: (X, \tau) \rightarrow (Y, \sigma)$ is called semi-open [9] (resp. regular open [11], resp. α -open [15], resp. gs -open [25], resp. gsp -open [6], resp. gb -open [24], resp. rgb -open [8], resp. g -open [13], resp. αg -open [5], resp. wg -open [16], resp. rwg -open [16], resp. rg -open [2], resp. gpr -open [7]) if for every open subset U of (X, τ) , the set $f(U)$ is semi-open (resp. regular open, resp. α -open, resp. gs -open, resp. gsp -open, resp. gb -open, resp. rgb -open, resp. g -open, resp. αg -open, resp. wg -open, resp. rwg -open, resp. rg -open, resp. gpr -open) in (Y, σ) .

Definition 2.6

For a subset A of a space X , *sαrps*-closure is defined as,

$$s\alpha rps-clA = \bigcap \{F: A \subseteq F \text{ and } F \text{ is } s\alpha rps\text{-closed in } X\}.$$

Lemma 2.7

- (i) If $A \subseteq B$, then $s\alpha rps-clA \subseteq s\alpha rps-clB$.

- (ii) If $A \subseteq B$, then $sarps\text{-}intA \subseteq sarps\text{-}intB$.
- (iii) $A \subseteq sarps\text{-}clB$.
- (iv) $sarps\text{-}intA \subseteq A$.
- (v) A is $sarps\text{-}closed$ if and only if $sarps\text{-}clA = A$.
- (vi) A is $sarps\text{-}open$ if and only if $sarps\text{-}intA = A$.

Lemma 2.8 [19]

If a subset N of space X is $sarps\text{-}open$, then N is a $sarps\text{-}nbhd$ of each of its points.

Definition 2.9

- (i) A function $f: (X, \tau) \rightarrow (Y, \sigma)$ is called $g\text{-continuous}$ [4] if $f^{-1}(V)$ is $g\text{-closed}$ in (X, τ) for every closed subset V of (Y, σ) .
- (ii) A function $f: (X, \tau) \rightarrow (Y, \sigma)$ is called $sarps\text{-}continuous$ [20] if $f^{-1}(V)$ is $sarps\text{-}closed$ in (X, τ) for every closed subset V of (Y, σ) .
- (iii) A function $f: (X, \tau) \rightarrow (Y, \sigma)$ is called $sarps\text{-}irresolute$ [20] if $f^{-1}(V)$ is $sarps\text{-}closed$ in (X, τ) for every $sarps\text{-}closed$ subset V of (Y, σ) .
- (iv) A function $f: (X, \tau) \rightarrow (Y, \sigma)$ is called strongly $sarps\text{-}continuous$ if $f^{-1}(V)$ is closed in (X, τ) for every $sarps\text{-}closed$ subset V of (Y, σ) .

Definition 2.10 [10]

A space X is called a $T_{1/2}$ space if every $g\text{-closed}$ set is closed.

III. SARPS-CLOSED MAPS IN TOPOLOGICAL SPACES

In this section, we introduce $sarps\text{-}closed$ maps in topological spaces.

Definition 3.1

A map $f: (X, \tau) \rightarrow (Y, \sigma)$ is called $sarps\text{-}closed$ if for every closed subset F of (X, τ) , $f(F)$ is a $sarps\text{-}closed$ set in (Y, σ) .

Proposition 3.2

Every closed map is a $sarps\text{-}closed$ map.

Proof

Let $f: (X, \tau) \rightarrow (Y, \sigma)$ be a closed map. Let F be a closed subset of (X, τ) . Since f is a closed map, $f(F)$ is a closed set in (Y, σ) . Since every closed set is $sarps\text{-}closed$, $f(F)$ is $sarps\text{-}closed$ in (Y, σ) . Therefore f is a $sarps\text{-}closed$ map.

Converse of the above Proposition need not be true as shown in Example 3.4.

Proposition 3.3

- (i) Every semi-closed map is a $sarps\text{-}closed$ map.
- (ii) Every regular closed map is a $sarps\text{-}closed$ map.
- (iii) Every $\alpha\text{-closed}$ map is a $sarps\text{-}closed$ map.

Proof

Let $f: (X, \tau) \rightarrow (Y, \sigma)$ be a semi-closed (resp. regular closed, resp. $\alpha\text{-closed}$) map. Let F be a closed subset of (X, τ) . Since f is a semi-closed (resp. regular closed, resp. $\alpha\text{-closed}$) map, $f(F)$ is a semi-closed (resp. regular closed, resp. $\alpha\text{-closed}$) set in (Y, σ) . By Proposition 3.2 of [22], $f(F)$ is

$sarps\text{-}closed$ in (Y, σ) . Therefore f is a $sarps\text{-}closed$ map.

Converse of the above Proposition need not be true as shown in Example 3.4.

Example 3.4

Let $X = Y = \{a,b,c\}$ with topologies $\tau = \{\emptyset, \{a\}, X\}$ and $\sigma = \{\emptyset, \{a\}, \{b,c\}, Y\}$ on X and Y respectively. Let the map $f: (X, \tau) \rightarrow (Y, \sigma)$ be defined as $f(a) = b, f(b) = c, f(c) = a$.

Here the closed sets in (X, τ) are $\emptyset, \{b,c\}$ and X . Now $f(\{b,c\}) = \{a,c\}$, which is $sarps\text{-}closed$ in (Y, σ) . Therefore for every closed set F in (X, τ) , $f(F)$ is $sarps\text{-}closed$ in (Y, σ) . Hence f is $sarps\text{-}closed$. But $\{a,c\}$ is not closed, not semi-closed, not regular closed, not $\alpha\text{-closed}$ in (Y, σ) . Hence f is not closed, not semi-closed, not regular closed, not $\alpha\text{-closed}$.

Proposition 3.5

- (i) Every $sarps\text{-}closed$ map is a $gs\text{-}closed$ map.
- (ii) Every $sarps\text{-}closed$ map is a $gsp\text{-}closed$ map.
- (iii) Every $sarps\text{-}closed$ map is a $gb\text{-}closed$ map.
- (iv) Every $sarps\text{-}closed$ map is a $rgb\text{-}closed$ map.

Proof

Let $f: (X, \tau) \rightarrow (Y, \sigma)$ be a $sarps\text{-}closed$ map. Let F be a closed subset of (X, τ) . Since f is a $sarps\text{-}closed$ map, $f(F)$ is a $sarps\text{-}closed$ set in (Y, σ) . By Proposition 3.4 of [22], $f(F)$ is $gs\text{-}closed$ (resp. $gsp\text{-}closed$, resp. $gb\text{-}closed$, resp. $rgb\text{-}closed$) in (Y, σ) . Therefore f is a $gs\text{-}closed$ (resp. $gsp\text{-}closed$, resp. $gb\text{-}closed$, resp. $rgb\text{-}closed$) map.

Converse of the above Proposition need not be true as shown in Example 3.6.

Example 3.6

Let $X = Y = \{a,b,c,d\}$ with topologies $\tau = \{\emptyset, \{b,d\}, X\}$ and $\sigma = \{\emptyset, \{a\}, \{b\}, \{a,b\}, \{b,c\}, \{a,b,c\}, Y\}$ on X and Y respectively. Let the map $f: (X, \tau) \rightarrow (Y, \sigma)$ be defined as $f(a) = b, f(b) = c, f(c) = d, f(d) = a$. Here the closed sets in (X, τ) are $\emptyset, \{a,c\}$ and X . Now $f(\{a,c\}) = \{b,d\}$ is $gs\text{-}closed$ (resp. $gb\text{-}closed$, resp. $gsp\text{-}closed$, resp. $rgb\text{-}closed$) in (Y, σ) . Therefore f is $gs\text{-}closed$ (resp. $gb\text{-}closed$, resp. $gsp\text{-}closed$, resp. $rgb\text{-}closed$). But $\{b,d\}$ is not $sarps\text{-}closed$ in (Y, σ) . Hence f is not $sarps\text{-}closed$.

The concept $sarps\text{-}closed$ map is independent from the concepts $ag\text{-}closed$ map, $g\text{-closed}$ map, $rg\text{-closed}$ map, $gpr\text{-}closed$ map, $wg\text{-closed}$ map, $rwg\text{-closed}$ map as shown in the following examples.

Example 3.7

Let $X = Y = \{a,b,c,d\}$ with topologies $\tau = \{\emptyset, \{a,c\}, X\}$ and $\sigma = \{\emptyset, \{a\}, \{b\}, \{a,b\}, \{b,c\}, \{a,b,c\}, Y\}$ on X and Y respectively. Let the map $f: (X, \tau) \rightarrow (Y, \sigma)$ be defined as $f(a) = b, f(b) = c, f(c) = d, f(d) = a$. Here the closed sets in (X, τ) are $\emptyset, \{b,d\}$ and X . Now $f(\{b,d\}) = \{a,c\}$ is

sarps-closed, but not *ag*-closed in (Y, σ) . Hence f is *sarps*-closed, but not *ag*-closed.

Example 3.8

Let $X = Y = \{a, b, c, d\}$ with topologies $\tau = \{\emptyset, \{b, d\}, X\}$ and $\sigma = \{\emptyset, \{a\}, \{b\}, \{a, b\}, \{b, c\}, \{a, b, c\}, Y\}$ on X and Y respectively. Let the map $f: (X, \tau) \rightarrow (Y, \sigma)$ be defined as $f(a) = b, f(b) = c, f(c) = d, f(d) = a$. Here the closed sets in (X, τ) are $\emptyset, \{a, c\}$ and X . Now $f(\{a, c\}) = \{b, d\}$ is

ag-closed, but not *sarps*-closed in (Y, σ) . Hence f is *ag*-closed, but not *sarps*-closed.

Example 3.9

Let $X = Y = \{a, b, c, d\}$ with topologies $\tau = \{\emptyset, \{a, b\}, X\}$ and $\sigma = \{\emptyset, \{a\}, \{b\}, \{a, b\}, \{a, b, c\}, \{a, b, d\}, Y\}$ on X and Y respectively. Let the map $f: (X, \tau) \rightarrow (Y, \sigma)$ be defined as $f(a) = b, f(b) = c, f(c) = f(d) = a$. Here the closed sets in (X, τ) are $\emptyset, \{c, d\}$ and X . Now $f(\{c, d\}) = \{a\}$ is *sarps*-closed, but not *rg*-closed in (Y, σ) . Hence f is *sarps*-closed, but not *rg*-closed.

Example 3.10

Let $X = Y = \{a, b, c, d\}$ with topologies $\tau = \{\emptyset, \{d\}, X\}$ and $\sigma = \{\emptyset, \{a\}, \{b\}, \{a, b\}, \{a, b, c\}, \{a, b, d\}, Y\}$ on X and Y respectively. Let the map $f: (X, \tau) \rightarrow (Y, \sigma)$ be defined as $f(a) = a, f(b) = b, f(c) = c, f(d) = d$. Here the closed sets in (X, τ) are $\emptyset, \{a, b, c\}$ and X . Now $f(\{a, b, c\}) = \{a, b, c\}$ is *rg*-closed, but not *sarps*-closed in (Y, σ) . Hence f is *rg*-closed, but not *sarps*-closed.

Example 3.11

Let $X = Y = \{a, b, c, d\}$ with topologies $\tau = \{\emptyset, \{b, c\}, X\}$ and $\sigma = \{\emptyset, \{a\}, \{a, b\}, Y\}$ on X and Y respectively. Let the map $f: (X, \tau) \rightarrow (Y, \sigma)$ be defined as $f(a) = b, f(b) = c, f(c) = d, f(d) = b$. Here the closed sets in (X, τ) are $\emptyset, \{a, d\}$ and X . Now $f(\{a, d\}) = \{b\}$ is *sarps*-closed, but not *g*-closed in (Y, σ) . Hence f is *sarps*-closed, but not *g*-closed.

Example 3.12

Let $X = Y = \{a, b, c, d\}$ with topologies $\tau = \{\emptyset, \{a, c\}, X\}$ and $\sigma = \{\emptyset, \{a\}, \{a, b\}, Y\}$ on X and Y respectively. Let the map $f: (X, \tau) \rightarrow (Y, \sigma)$ be defined as $f(a) = b, f(b) = c, f(c) = d, f(d) = a$. Here the closed sets in (X, τ) are $\emptyset, \{b, d\}$ and X . Now $f(\{b, d\}) = \{a, c\}$ is *g*-closed, but not *sarps*-closed in (Y, σ) . Hence f is *g*-closed, but not *sarps*-closed.

Example 3.13

Let $X = Y = \{a, b, c\}$ with topologies $\tau = \{\emptyset, \{a\}, X\}$ and $\sigma = \{\emptyset, \{a\}, \{b\}, \{a, b\}, Y\}$ on X and Y respectively. Let the map $f: (X, \tau) \rightarrow (Y, \sigma)$ be defined as $f(a) = b, f(b) = f(c) = a$. Here the closed sets in (X, τ) are $\emptyset, \{b, c\}$ and X . Now $f(\{b, c\}) = \{a\}$ is *sarps*-closed, but not *gpr*-closed in (Y, σ) . Hence f is *sarps*-closed, but not *gpr*-closed.

Example 3.14

Let $X = Y = \{a, b, c\}$ with topologies $\tau = \{\emptyset, \{a\}, X\}$ and $\sigma = \{\emptyset, \{a\}, \{b\}, \{a, b\}, Y\}$ on X and Y respectively. Let the map $f: (X, \tau) \rightarrow (Y, \sigma)$ be defined as $f(a) = c, f(b) = b, f(c) = a$. Here the closed sets in (X, τ) are $\emptyset, \{b, c\}$ and X . Now $f(\{b, c\}) = \{a, b\}$ is *gpr*-closed, but not *sarps*-closed in (Y, σ) . Hence f is *gpr*-closed, but not *sarps*-closed.

Example 3.15

Let $X = Y = \{a, b, c, d\}$ with topologies $\tau = \{\emptyset, \{a\}, X\}$ and $\sigma = \{\emptyset, \{a\}, \{b\}, \{a, b\}, \{a, b, c\}, Y\}$ on X and Y respectively. Let the map $f: (X, \tau) \rightarrow (Y, \sigma)$ be defined as $f(a) = b, f(b) = f(c) = f(d) = a$. Here the closed sets in (X, τ) are $\emptyset, \{b, c, d\}$ and X . Now $f(\{b, c, d\}) = \{a\}$ is *sarps*-closed, but not *wg*-closed and not *rwg*-closed in (Y, σ) . Hence f is *sarps*-closed, but not *wg*-closed and not *rwg*-closed.

Example 3.16

Let $X = Y = \{a, b, c, d\}$ with topologies $\tau = \{\emptyset, \{a\}, X\}$ and $\sigma = \{\emptyset, \{a\}, \{b\}, \{a, b\}, \{a, b, c\}, Y\}$ on X and Y respectively. Let the map $f: (X, \tau) \rightarrow (Y, \sigma)$ be defined as $f(a) = c, f(b) = a, f(c) = d, f(d) = b$. Here the closed sets in (X, τ) are $\emptyset, \{b, c, d\}$ and X . Now $f(\{b, c, d\}) = \{a, b, d\}$ is *wg*-closed and *rwg*-closed, but not *sarps*-closed in (Y, σ) . Hence f is *wg*-closed and *rwg*-closed, but not *sarps*-closed.

Theorem 3.17

A map $f: (X, \tau) \rightarrow (Y, \sigma)$ is *sarps*-closed if and only if for each subset S of (Y, σ) and for each open set U containing $f^{-1}(S)$, there exists a *sarps*-open set V of (Y, σ) such that $S \subseteq V$ and $f^{-1}(V) \subseteq U$.

Proof

Assume that f is *sarps*-closed. Let S be a subset of (Y, σ) and U be an open set containing $f^{-1}(S)$. Then $X \setminus U$ is a closed set in (X, τ) not containing $f^{-1}(S)$. Since f is *sarps*-closed, $f(X \setminus U)$ is *sarps*-closed in (Y, σ) not containing S . Therefore $Y \setminus f(X \setminus U)$ is a *sarps*-open set in (Y, σ) containing S . Let $V = Y \setminus f(X \setminus U)$. Hence V is a *sarps*-open set in (Y, σ) such that $S \subseteq V$ and $f^{-1}(V) \subseteq U$.

Conversely, let F be a closed set in (X, τ) . Then $X \setminus F$ is an open set in (X, τ) and $f(F)$ is a subset of (Y, σ) and so $Y \setminus f(F)$ is a subset of (Y, σ) . Therefore $f^{-1}(Y \setminus f(F))$ is a subset of (X, τ) . Take $S = Y \setminus f(F)$ and $U = X \setminus F$. Therefore $f^{-1}(S) \subseteq U$. By hypothesis, there exists a *sarps*-open set V of (Y, σ) such that $S \subseteq V$ and $f^{-1}(V) \subseteq U$. That is, $Y \setminus f(F) \subseteq V$ and $f^{-1}(V) \subseteq X \setminus F$. Then we have $F \subseteq X \setminus f^{-1}(V)$ and $Y \setminus V \subseteq f(F) \subseteq f(X \setminus f^{-1}(V)) \subseteq Y \setminus V$ which implies $Y \setminus V = f(F)$. Since V is *sarps*-open in (Y, σ) , $Y \setminus V$ is *sarps*-closed in (Y, σ) . Therefore $f(F)$ is *sarps*-closed in (Y, σ) . Hence f is *sarps*-closed.

Theorem 3.18

If $f: (X, \tau) \rightarrow (Y, \sigma)$ is a continuous, *sarps*-closed surjection and if (X, τ) is a normal space, then (Y, σ) is normal.

Proof

Let A and B be two disjoint closed subsets of (Y, σ) . Since f is a continuous surjection, $f^{-1}(A)$ and $f^{-1}(B)$ are the disjoint closed sets in (X, τ) . Since (X, τ) is normal, there exist disjoint open sets U and V such that $f^{-1}(A) \subseteq U$ and $f^{-1}(B) \subseteq V$. Since f is *sarps*-closed, by Theorem 3.17, there exist *sarps*-open sets G and H of (Y, σ) such that $A \subseteq G$, $B \subseteq H$ and $f^{-1}(G) \subseteq U$, $f^{-1}(H) \subseteq V$. Then we have $f^{-1}(G) \cap f^{-1}(H) = \emptyset$ and so $G \cap H = \emptyset$. Since every closed set is *arps*-closed, A is *arps*-closed. Since G is *sarps*-open and $A \subseteq G$, by Theorem 3.17 of [19],

$A \subseteq \text{int}G$. Similarly $B \subseteq \text{int}H$. Since $\text{int}G \cap \text{int}H = \emptyset$, $(\text{int} \text{cl} \text{int} \text{int}G) \cap (\text{int} \text{cl} \text{int} \text{int}H) = \emptyset$.

Since $A \subseteq \text{int}G \subseteq \text{int} \text{cl} \text{int} \text{int}G$ and

$B \subseteq \text{int}H \subseteq \text{int} \text{cl} \text{int} \text{int}H$, (Y, σ) is normal.

Theorem 3.19

If a mapping $f: (X, \tau) \rightarrow (Y, \sigma)$ is *sarps*-closed, then $\text{sarps-cl}(f(A)) \subseteq f(\text{cl}A)$ for every subset A of (X, τ) .

Proof

Suppose that f is *sarps*-closed and $A \subseteq X$. Then $\text{cl}A$ is closed in (X, τ) . Since f is *sarps*-closed, $f(\text{cl}A)$ is *sarps*-closed in (Y, σ) .

Therefore $\text{sarps-cl}(f(\text{cl}A)) = f(\text{cl}A)$.

We have $f(A) \subseteq f(\text{cl}A)$.

By Lemma 2.7(i), $\text{sarps-cl}(f(A)) \subseteq \text{sarps-cl}(f(\text{cl}A))$.

That is, $\text{sarps-cl}(f(A)) \subseteq f(\text{cl}A)$.

Theorem 3.20

Let $f: (X, \tau) \rightarrow (Y, \sigma)$ and $g: (Y, \sigma) \rightarrow (Z, \mu)$ be two mappings. Let $h = g \circ f$.

(i) If f is closed and g is *sarps*-closed, then h is *sarps*-closed.

(ii) If f is g -closed, g is *sarps*-closed and (Y, σ) is a $T_{1/2}$ space, then h is *sarps*-closed.

(iii) If f is regular closed and g is *sarps*-closed, then h is *sarps*-closed.

Proof

(i) Let F be closed in (X, τ) . Since f is closed, $f(F)$ is closed in (Y, σ) . Since g is *sarps*-closed, $g(f(F))$ is *sarps*-closed in (Z, μ) . That is $h(F)$ is *sarps*-closed in (Z, μ) . This proves (i).

(ii) Let F be closed in (X, τ) . Since f is g -closed, $f(F)$ is g -closed in (Y, σ) . Since (Y, σ) is a $T_{1/2}$ space, by Definition 2.10, $f(F)$ is closed in (Y, σ) . Since g is *sarps*-closed, $g(f(F))$ is *sarps*-closed in (Z, μ) . That is $h(F)$ is *sarps*-closed in (Z, μ) . This proves (ii).

(iii) Let F be closed in (X, τ) . Since f is regular closed, $f(F)$ is regular closed in (Y, σ) . Since every regular closed set is

closed, $f(F)$ is closed in (Y, σ) . Since g is *sarps*-closed, $g(f(F))$ is *sarps*-closed in (Z, μ) . That is $h(F)$ is *sarps*-closed in (Z, μ) . This proves (iii).

Theorem 3.21

Let $f: (X, \tau) \rightarrow (Y, \sigma)$ and $g: (Y, \sigma) \rightarrow (Z, \mu)$ be two mappings. Let $h = g \circ f$ be *sarps*-closed.

(i) If f is continuous and surjective, then g is *sarps*-closed.

(ii) If f is g -continuous and surjective and (X, τ) is a $T_{1/2}$ space, then g is *sarps*-closed.

(iii) If g is *sarps*-irresolute and injective, then f is *sarps*-closed.

(iv) If g is strongly *sarps*-continuous and injective, then f is *sarps*-closed.

Proof

(i) Let F be closed in (Y, σ) . Since f is continuous, $f^{-1}(F)$ is closed in (X, τ) . Since h is *sarps*-closed, $h(f^{-1}(F))$ is *sarps*-closed in (Z, μ) . That is $(g \circ f)(f^{-1}(F))$ is *sarps*-closed in (Z, μ) . That is $g(F)$ is *sarps*-closed in (Z, μ) . This proves (i).

(ii) Let F be closed in (Y, σ) . Since f is g -continuous, $f^{-1}(F)$ is g -closed in (X, τ) . Since (X, τ) is a $T_{1/2}$ space, $f^{-1}(F)$ is closed in (X, τ) . Since h is *sarps*-closed, $h(f^{-1}(F))$ is *sarps*-closed in (Z, μ) . That is $(g \circ f)(f^{-1}(F))$ is *sarps*-closed in (Z, μ) . That is $g(F)$ is *sarps*-closed in (Z, μ) . This proves (ii).

(iii) Let F be closed in (X, τ) . Since h is *sarps*-closed, $h(F)$ is *sarps*-closed in (Z, μ) . That is $g(f(F))$ is *sarps*-closed in (Z, μ) . Since g is *sarps*-irresolute, $g^{-1}(g(f(F)))$ is *sarps*-closed in (Y, σ) . That is $f(F)$ is *sarps*-closed in (Y, σ) . This proves (iii).

(iv) Let F be closed in (X, τ) . Since h is *sarps*-closed, $h(F)$ is *sarps*-closed in (Z, μ) . That is $g(f(F))$ is *sarps*-closed in (Z, μ) . Since g is strongly *sarps*-continuous, $g^{-1}(g(f(F)))$ is closed in (Y, σ) . That is $f(F)$ is closed in (Y, σ) . Since every closed set is *sarps*-closed, $f(F)$ is *sarps*-closed in (Y, σ) . This proves (iv).

IV. *SARPS*-OPEN MAPS IN TOPOLOGICAL SPACES

In this section, we introduce *sarps*-open maps in topological spaces.

Definition 4.1

A map $f: (X, \tau) \rightarrow (Y, \sigma)$ is called *sarps*-open if for every open subset U of (X, τ) , $f(U)$ is a *sarps*-open set in (Y, σ) .

Proposition 4.2

Every open map is a *sarps*-open map.

Proof

Let $f: (X, \tau) \rightarrow (Y, \sigma)$ be an open map. Let U be an open subset of (X, τ) . Since f is an open map, $f(U)$ is an open set in

(Y, σ) . Since every open set is *sarps*-open, $f(U)$ is *sarps*-open in (Y, σ) . Therefore f is a *sarps*-open map.

Converse of the above Proposition need not be true as shown in Example 4.4.

Proposition 4.3

- (i) Every semi-open map is a *sarps*-open map.
- (ii) Every regular open map is a *sarps*-open map.
- (iii) Every α -open map is a *sarps*-open map.

Proof

Let $f: (X, \tau) \rightarrow (Y, \sigma)$ be a semi-open (resp. regular open, resp. α -open) map. Let U be an open subset of (X, τ) . Since f is a semi-open (resp. regular open, resp. α -open) map, $f(U)$ is a semi-open (resp. regular open, resp. α -open) set in (Y, σ) . By Proposition 3.2 of [19], $f(U)$ is *sarps*-open in (Y, σ) . Therefore f is a *sarps*-open map.

Converse of the above Proposition need not be true as shown in Example 4.4.

Example 4.4

Let $X = Y = \{a, b, c\}$ with topologies $\tau = \{\emptyset, \{a\}, X\}$ and $\sigma = \{\emptyset, \{a\}, \{b, c\}, Y\}$ on X and Y respectively. Let the map $f: (X, \tau) \rightarrow (Y, \sigma)$ be defined as $f(a) = b, f(b) = c, f(c) = a$.

Here the open sets in (X, τ) are $\emptyset, \{a\}$ and X . Now $f(\{a\}) = \{b\}$, which is *sarps*-open in (Y, σ) . Therefore for every open set U in (X, τ) , $f(U)$ is *sarps*-open in (Y, σ) . Hence f is *sarps*-open. But $\{b\}$ is not open, not semi-open, not regular open, not α -open in (Y, σ) . Hence f is not open, not semi-open, not regular open, not α -open.

Proposition 4.5

- (i) Every *sarps*-open map is a *gs*-open map.
- (ii) Every *sarps*-open map is a *gsp*-open map.
- (iii) Every *sarps*-open map is a *gb*-open map.
- (iv) Every *sarps*-open map is a *rgb*-open map.

Proof

Let $f: (X, \tau) \rightarrow (Y, \sigma)$ be a *sarps*-open map. Let U be an open subset of (X, τ) . Since f is a *sarps*-open map, $f(U)$ is a *sarps*-open set in (Y, σ) . By Proposition 3.4 of [19], $f(U)$ is *gs*-open (resp. *gsp*-open, resp. *gb*-open, resp. *rgb*-open) in (Y, σ) . Therefore f is a *gs*-open (resp. *gsp*-open, resp. *gb*-open, resp. *rgb*-open) map.

Converse of the above Proposition need not be true as shown in Example 4.6.

Example 4.6

Let $X = Y = \{a, b, c, d\}$ with topologies $\tau = \{\emptyset, \{b, d\}, X\}$ and $\sigma = \{\emptyset, \{a\}, \{b\}, \{a, b\}, \{b, c\}, \{a, b, c\}, Y\}$ on X and Y respectively. Let the map $f: (X, \tau) \rightarrow (Y, \sigma)$ be defined as $f(a) = b, f(b) = c, f(c) = d, f(d) = a$. Here the open sets in (X, τ) are $\emptyset, \{b, d\}$ and X . Now $f(\{b, d\}) = \{a, c\}$ is *gs*-open (resp. *gb*-open, resp. *gsp*-open, resp. *rgb*-open) in (Y, σ) . Therefore f is *gs*-open (resp. *gb*-open, resp. *gsp*-open, resp.

rgb-open). But $\{a, c\}$ is not *sarps*-open in (Y, σ) . Hence f is not *sarps*-open.

The concept *sarps*-open map is independent from the concepts αg -open map, *g*-open map, *rg*-open map, *gpr*-open map, *wg*-open map, *rwg*-open map as shown in the following examples.

Example 4.7

Let $X = Y = \{a, b, c, d\}$ with topologies $\tau = \{\emptyset, \{a, c\}, X\}$ and $\sigma = \{\emptyset, \{a\}, \{b\}, \{a, b\}, \{b, c\}, \{a, b, c\}, Y\}$ on X and Y respectively. Let the map $f: (X, \tau) \rightarrow (Y, \sigma)$ be defined as $f(a) = b, f(b) = c, f(c) = d, f(d) = a$. Here the open sets in (X, τ) are $\emptyset, \{a, c\}$ and X . Now $f(\{a, c\}) = \{b, d\}$ is

sarps-open, but not αg -open in (Y, σ) . Hence f is *sarps*-open, but not αg -open.

Example 4.8

Let $X = Y = \{a, b, c, d\}$ with topologies $\tau = \{\emptyset, \{b, d\}, X\}$ and $\sigma = \{\emptyset, \{a\}, \{b\}, \{a, b\}, \{b, c\}, \{a, b, c\}, Y\}$ on X and Y respectively. Let the map $f: (X, \tau) \rightarrow (Y, \sigma)$ be defined as $f(a) = b, f(b) = c, f(c) = d, f(d) = a$. Here the open sets in (X, τ) are $\emptyset, \{b, d\}$ and X . Now $f(\{b, d\}) = \{a, c\}$ is αg -open,

but not *sarps*-open in (Y, σ) . Hence f is αg -open, but not *sarps*-open.

Example 4.9

Let $X = Y = \{a, b, c, d\}$ with topologies $\tau = \{\emptyset, \{a, b, c\}, X\}$ and $\sigma = \{\emptyset, \{a\}, \{b\}, \{a, b\}, \{a, b, c\}, \{a, b, d\}, Y\}$ on X and Y respectively. Let the map $f: (X, \tau) \rightarrow (Y, \sigma)$ be defined as $f(a) = b, f(b) = c, f(c) = d, f(d) = a$. Here the open sets in (X, τ) are $\emptyset, \{a, b, c\}$ and X . Now $f(\{a, b, c\}) = \{b, c, d\}$ is *sarps*-open, but not *rg*-open in (Y, σ) . Hence f is *sarps*-open, but not *rg*-open.

Example 4.10

Let $X = Y = \{a, b, c, d\}$ with topologies $\tau = \{\emptyset, \{c\}, X\}$ and $\sigma = \{\emptyset, \{a\}, \{b\}, \{a, b\}, \{a, b, c\}, \{a, b, d\}, Y\}$ on X and Y respectively. Let the map $f: (X, \tau) \rightarrow (Y, \sigma)$ be defined as $f(a) = b, f(b) = c, f(c) = d, f(d) = a$. Here the open sets in (X, τ) are $\emptyset, \{c\}$ and X . Now $f(\{c\}) = \{d\}$ is *rg*-open, but not *sarps*-open in (Y, σ) . Hence f is *rg*-open, but not *sarps*-open.

Example 4.11

Let $X = Y = \{a, b, c, d\}$ with topologies $\tau = \{\emptyset, \{b, c, d\}, X\}$ and $\sigma = \{\emptyset, \{a\}, \{a, b\}, Y\}$ on X and Y respectively. Let the map $f: (X, \tau) \rightarrow (Y, \sigma)$ be defined as $f(a) = b, f(b) = c, f(c) = d, f(d) = a$. Here the open sets in (X, τ) are $\emptyset, \{b, c, d\}$ and X . Now $f(\{b, c, d\}) = \{a, c, d\}$ is *sarps*-open, but not *g*-open in (Y, σ) . Hence f is *sarps*-open, but not *g*-open.

Example 4.12

Let $X = Y = \{a, b, c, d\}$ with topologies $\tau = \{\phi, \{a, c\}, X\}$ and $\sigma = \{\phi, \{a\}, \{a, b\}, Y\}$ on X and Y respectively. Let the map $f: (X, \tau) \rightarrow (Y, \sigma)$ be defined as $f(a) = b, f(b) = c, f(c) = d, f(d) = a$. Here the open sets in (X, τ) are $\phi, \{a, c\}$ and X . Now $f(\{a, c\}) = \{b, d\}$ is g -open, but not $sarps$ -open in (Y, σ) . Hence f is g -open, but not $sarps$ -open.

Example 4.13

Let $X = Y = \{a, b, c\}$ with topologies $\tau = \{\phi, \{a, b\}, X\}$ and $\sigma = \{\phi, \{a\}, \{b\}, \{a, b\}, Y\}$ on X and Y respectively. Let the map $f: (X, \tau) \rightarrow (Y, \sigma)$ be defined as $f(a) = b, f(b) = c, f(c) = a$. Here the open sets in (X, τ) are $\phi, \{a, b\}$ and X . Now $f(\{a, b\}) = \{b, c\}$ is $sarps$ -open, but not gpr -open in (Y, σ) . Hence f is $sarps$ -open, but not gpr -open.

Example 4.14

Let $X = Y = \{a, b, c\}$ with topologies $\tau = \{\phi, \{a\}, X\}$ and $\sigma = \{\phi, \{a\}, \{b\}, \{a, b\}, Y\}$ on X and Y respectively. Let the map $f: (X, \tau) \rightarrow (Y, \sigma)$ be defined as $f(a) = c, f(b) = b, f(c) = a$. Here the open sets in (X, τ) are $\phi, \{a\}$ and X . Now $f(\{a\}) = \{c\}$ is gpr -open, but not $sarps$ -open in (Y, σ) . Hence f is gpr -open, but not $sarps$ -open.

Example 4.15

Let $X = Y = \{a, b, c, d\}$ with topologies $\tau = \{\phi, \{a, b, c\}, X\}$ and $\sigma = \{\phi, \{a\}, \{b\}, \{a, b\}, \{a, b, c\}, Y\}$ on X and Y respectively. Let the map $f: (X, \tau) \rightarrow (Y, \sigma)$ be defined as $f(a) = b, f(b) = c, f(c) = d, f(d) = a$. Here the open sets in (X, τ) are $\phi, \{a, b, c\}$ and X . Now $f(\{a, b, c\}) = \{b, c, d\}$ is $sarps$ -open, but not wg -open and not rwg -open in (Y, σ) . Hence f is $sarps$ -open, but not wg -open and not rwg -open.

Example 4.16

Let $X = Y = \{a, b, c, d\}$ with topologies $\tau = \{\phi, \{a\}, X\}$ and $\sigma = \{\phi, \{a\}, \{b\}, \{a, b\}, \{a, b, c\}, Y\}$ on X and Y respectively. Let the map $f: (X, \tau) \rightarrow (Y, \sigma)$ be defined as $f(a) = c, f(b) = a, f(c) = d, f(d) = b$. Here the open sets in (X, τ) are $\phi, \{a\}$ and X . Now $f(\{a\}) = \{c\}$ is wg -open and rwg -open, but not $sarps$ -open in (Y, σ) . Hence f is wg -open and rwg -open, but not $sarps$ -open.

Theorem 4.17

If a mapping $f: (X, \tau) \rightarrow (Y, \sigma)$ is $sarps$ -open, then $f(intA) \subseteq sarps-int(f(A))$ for every subset A of (X, τ) .

Proof

Suppose that f is $sarps$ -open and $A \subseteq X$. Then $intA$ is open in (X, τ) . Since f is $sarps$ -open, $f(intA)$ is $sarps$ -open in (Y, σ) . By Lemma 2.7(vi), $sarps-int(f(intA)) = f(intA)$. We have $f(intA) \subseteq f(A)$. By Lemma 2.7(ii), $sarps-int(f(intA)) \subseteq sarps-int(f(A))$. That is $f(intA) \subseteq sarps-int(f(A))$.

Theorem 4.18

If a map $f: (X, \tau) \rightarrow (Y, \sigma)$ is $sarps$ -open, then for each nbhd U of x in (X, τ) , there exists a $sarps$ -nbhd W of $f(x)$ in (Y, σ) such that $W \subseteq f(U)$.

Proof

Let $f: (X, \tau) \rightarrow (Y, \sigma)$ be $sarps$ -open. Let $x \in X$ and U be an arbitrary nbhd of x in (X, τ) . Then there exists an open set G in (X, τ) such that $x \in G \subseteq U$. Now $f(x) \in f(G) \subseteq f(U)$ and $f(G)$ is a $sarps$ -open set in (Y, σ) , as f is a $sarps$ -open map. By Lemma 2.8, $f(G)$ is a $sarps$ -nbhd of each of its points. Taking $f(G) = W$, W is a $sarps$ -nbhd of $f(x)$ in (Y, σ) such that $W \subseteq f(U)$.

Theorem 4.19

A map $f: (X, \tau) \rightarrow (Y, \sigma)$ is $sarps$ -open if and only if for any subset S of (Y, σ) and any closed set F of (X, τ) containing $f^{-1}(S)$, there exists a $sarps$ -closed set K of (Y, σ) containing S such that $f^{-1}(K) \subseteq F$.

Proof

Suppose f is a $sarps$ -open map. Let $S \subseteq Y$ and F be a closed set of (X, τ) such that $f^{-1}(S) \subseteq F$. Now $X \setminus F$ is an open set in (X, τ) . Since f is $sarps$ -open, $f(X \setminus F)$ is $sarps$ -open in (Y, σ) . Then $K = Y \setminus f(X \setminus F)$ is $sarps$ -closed in (Y, σ) . Now $f^{-1}(S) \subseteq F$ implies $S \subseteq K$ and $f^{-1}(K) = f^{-1}(Y \setminus f(X \setminus F)) \subseteq f^{-1}(Y) \setminus (X \setminus F) = F$. That is $f^{-1}(K) \subseteq F$. Conversely, let U be an open set of (X, τ) . Then $f(U)$ is a subset of (Y, σ) and so $Y \setminus f(U)$ is a subset of (Y, σ) . Therefore $f^{-1}(Y \setminus f(U)) \subseteq X \setminus U$. By hypothesis, there exists a $sarps$ -closed set K of (Y, σ) such that $Y \setminus f(U) \subseteq K$ and $f^{-1}(K) \subseteq X \setminus U$ and so $U \subseteq X \setminus f^{-1}(K)$. Hence $Y \setminus K \subseteq f(U) \subseteq f(X \setminus f^{-1}(K)) \subseteq Y \setminus K$ which implies $f(U) = Y \setminus K$. Since $Y \setminus K$ is $sarps$ -open in (Y, σ) , $f(U)$ is $sarps$ -open in (Y, σ) . Therefore f is a $sarps$ -open map.

Theorem 4.20

If a mapping $f: (X, \tau) \rightarrow (Y, \sigma)$ is $sarps$ -open, then $f^{-1}(sarps-clB) \subseteq cl f^{-1}(B)$ for every subset B of (Y, σ) .

Proof

Let $f: (X, \tau) \rightarrow (Y, \sigma)$ be $sarps$ -open and B be any subset of (Y, σ) . Then $f^{-1}(B) \subseteq cl f^{-1}(B)$ and $cl f^{-1}(B)$ is closed in (X, τ) . By Theorem 4.19, there exist a $sarps$ -closed set K of (Y, σ) such that $B \subseteq K$ and $f^{-1}(K) \subseteq cl f^{-1}(B)$. Since K is $sarps$ -closed, by Lemma 2.7(v), $sarps-clK = K$.

Since $B \subseteq K$, by Lemma 2.7(i),

$sarps-clB \subseteq sarps-clK = K$. Therefore $f^{-1}(sarps-clB) \subseteq f^{-1}(K) \subseteq cl f^{-1}(B)$. Thus $f^{-1}(sarps-clB) \subseteq cl f^{-1}(B)$.

Theorem 4.21

Let $f: (X, \tau) \rightarrow (Y, \sigma)$ and $g: (Y, \sigma) \rightarrow (Z, \mu)$ be two mappings. Let $h = g \circ f$.

(i) If f is open and g is $sarps$ -open, then h is $sarps$ -open.

(ii) If f is regular open and g is *sarps*-open, then h is *sarps*-open.

Proof

(i) Let F be open in (X, τ) . Since f is open, $f(F)$ is open in (Y, σ) . Since g is *sarps*-open, $g(f(F))$ is *sarps*-open in (Z, μ) . That is $h(F)$ is *sarps*-open in (Z, μ) .

This proves (i).

(ii) Let F be open in (X, τ) . Since f is regular open, $f(F)$ is regular open in (Y, σ) . Since every regular open set is open, $f(F)$ is open in (Y, σ) . Since g is *sarps*-open, $g(f(F))$ is *sarps*-open in (Z, μ) . That is $h(F)$ is *sarps*-open in (Z, μ) . This proves (ii).

Theorem 4.22

Let $f: (X, \tau) \rightarrow (Y, \sigma)$ and $g: (Y, \sigma) \rightarrow (Z, \mu)$ be two mappings. Let $h = g \circ f$ be *sarps*-open.

(i) If f is continuous and surjective, then g is *sarps*-open.

(ii) If g is *sarps*-irresolute and injective, then f is *sarps*-open.

(iii) If g is strongly *sarps*-continuous and injective, then f is *sarps*-open.

Proof

(i) Let F be open in (Y, σ) . Since f is continuous, $f^{-1}(F)$ is open in (X, τ) . Since h is *sarps*-open, $h(f^{-1}(F))$ is *sarps*-open in (Z, μ) . That is $(g \circ f)(f^{-1}(F))$ is *sarps*-open in (Z, μ) . That is $g(F)$ is *sarps*-open in (Z, μ) . This proves (i).

(ii) Let F be open in (X, τ) . Since h is *sarps*-open, $h(F)$ is *sarps*-open in (Z, μ) . That is $g(f(F))$ is *sarps*-open in (Z, μ) . Since g is *sarps*-irresolute, $g^{-1}(g(f(F)))$ is *sarps*-open in (Y, σ) . That is $f(F)$ is *sarps*-open in (Y, σ) . This proves (ii).

(iii) Let F be open in (X, τ) . Since h is *sarps*-open, $h(F)$ is *sarps*-open in (Z, μ) . That is $g(f(F))$ is *sarps*-open in (Z, μ) . Since g is strongly *sarps*-continuous, $g^{-1}(g(f(F)))$ is open in (Y, σ) . That is $f(F)$ is open in (Y, σ) . Since every open set is *sarps*-open, $f(F)$ is *sarps*-open in (Y, σ) . This proves (iii).

Theorem 4.23

Let $f: (X, \tau) \rightarrow (Y, \sigma)$ be a bijection. Then the following are equivalent.

(i) f is *sarps*-open.

(ii) f is *sarps*-closed.

(iii) f^{-1} is *sarps*-continuous.

Proof

(i) \Rightarrow (ii)

Suppose f is *sarps*-open. Let F be closed in (X, τ) . Then

$X \setminus F$ is open in (X, τ) . Since f is *sarps*-open, $f(X \setminus F)$ is *sarps*-open in (Y, σ) . Since f is a bijection, $Y \setminus f(F)$ is *sarps*-open in (Y, σ) . Therefore $f(F)$ is *sarps*-closed in (Y, σ) .

(ii) \Rightarrow (iii)

Suppose f is *sarps*-closed. Let $g = f^{-1}$. Let U be open in (X, τ) . Then $X \setminus U$ is closed in (X, τ) . Since f is *sarps*-closed, $f(X \setminus U)$ is *sarps*-closed in (Y, σ) . Since f is a bijection, $Y \setminus f(U)$ is *sarps*-closed that implies $f(U)$ is *sarps*-open in (Y, σ) . Since $g = f^{-1}$ and since f and g are bijection, $g^{-1}(U) = f(U)$ so that $g^{-1}(U)$ is *sarps*-open in (Y, σ) . Therefore f^{-1} is *sarps*-continuous.

(iii) \Rightarrow (i)

Suppose f^{-1} is *sarps*-continuous. Let U be open in (X, τ) . Then $X \setminus U$ is closed in (X, τ) . Since f^{-1} is *sarps*-continuous, $(f^{-1})^{-1}(X \setminus U) = f(X \setminus U) = Y \setminus f(U)$ is *sarps*-closed in (Y, σ) that implies $f(U)$ is *sarps*-open in (Y, σ) . Therefore f is *sarps*-open.

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